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## PATENT APPLICATION

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### SWIMMING POOL WATER LEVEL CONTROLLER

3 Inventors: J. Clifton Gibson and J. James Severt Docket No. 064743.000003

#### Field of the Invention

5 This invention relates in general to automatic water leveling systems, and in particular to  
6 a device for monitoring a swimming pool water level and supplying additional water when  
7 needed.

#### Background of the Invention

9 Conventional swimming pools and hot tubs include systems for recirculating the water in  
10 the pool or tub. As the pool water is recirculated, it is typically filtered and cleaned and may also  
11 be heated, if desired. Some pools have an automatic float level system. However, the majority  
12 of home pools do not have such a system for adding water to make up lost water due to  
13 evaporation and other causes. The home owner simply uses a garden hose from time to time to  
14 add water. This is time consuming and inconvenient.

15 Pools that have an automatic water level system often rely upon one or more float valves  
16 that are associated directly with the inlets and outlets for water entering and leaving the pool.  
17 When the water level in the pool rises or falls, the floats mechanically actuate valves to cause  
18 water to enter or leave the pool. Examples of these mechanical types of systems are shown in  
19 U.S. Patents Nos. 2,809,752, 3,837,015, and 3,895,402. Unfortunately, because the floats and  
20 valves of these systems are quite visible and located in or near the pool, they are vulnerable to

1 damage or vandalism from swimmers. The floats can be broken or rendered inoperable, thus  
2 negating the effectiveness of the system.

3 Systems are known that incorporate an overflow tank or sump that is separate from the  
4 pool. The level of the water in the separate tank is used as an indicator of the level of water in  
5 the swimming pool. This separate tank is then monitored using a sensor, float, or other device.  
6 Examples of these types of systems are shown in U.S. Patent Nos. 5,804,080, 4,445,238 and  
7 3,895,402. These systems have the advantage of allowing the components necessary to measure  
8 the liquid level in the pool to be located away from the main pool. However, because a separate  
9 tank is required to be associated with the pool, these systems must be installed when the pool is  
10 originally constructed. Otherwise, a retrofitting must be done wherein portions of the concrete  
11 surrounding the pool are broken up to install the separate tank and associated components. This  
12 can be costly and time-consuming and requires that the pool be closed down during installation.

13 U.S. Patent 5,878,447 shows a sensor for sensing the water level and sending a radio  
14 frequency transmission to a receiver. The receiver is electrically connected to a solenoid valve of  
15 a water source. While such a system is workable, improvements are desirable.

16 Summary of the Invention

17 The fluid leveler of this invention has a sensor that is immersed in the pool. A processor  
18 electrically connected with the sensor detects low water in the pool. A transmitter connected  
19 with the processor sends a radio frequency signal if the processor detects the low water. A  
20 waterproof housing contains the processor and transmitter circuitry and a battery for  
21 powering the processor and transmitter. A remote receiver receives the signal from the  
22 transmitter and turns on a valve to add water to the pool.

1        In the preferred embodiment, a tilt switch is connected between the battery and the  
2        processor for supplying power to the processor while in an on position. The tilt switch is  
3        enclosed within the housing and movable between the on and off position by tilting the  
4        housing. The tilt switch is in an off position when the housing is inverted from an  
5        operational position.

6        The processor preferably has a wave filter timer that turns on for a selected interval when  
7        the processor detects low water and delays the transmitter from sending the signal until the  
8        end of the selected interval. The processor causes the transmitter to send the signal at the end  
9        of the selected interval only if the processor continuously detects low water during the  
10       selected interval.

11       Preferably a power input of the transmitter is connected to an output of the processor so  
12       that the transmitter is supplied with power only when the processor directs the transmitter to  
13       send the signal. This reduces battery consumption. A low battery voltage detector is  
14       connected to the processor for informing the processor if low battery voltage is detected. The  
15       processor encodes a low battery voltage indication into the signal being sent by transmitter  
16       that indicates low water.

17       The receiver has an overfill counter that turns on for a selected interval when the receiver  
18       receives one of the signals from the transmitter. The overfill counter causes the valve to  
19       remain on until the overfill counter reaches a selected count. However, the receiver resets  
20       the overfill counter each time that the receiver receives one of the signals from the  
21       transmitter. This assures that a selected amount of overfill will occur.

23       **Brief Description of the Drawings**

24       Figure 1 is a schematic view illustrating a swimming pool recirculation system with a  
25       water leveler in accordance with this invention.

26       Figure 2 is an enlarged schematic view of portions of the water leveler of Figure 1.

27       Figure 3 is a side elevational view of the transmitter and sensor of the water leveler of  
28       Figure 2, with the cap of the housing shown removed.

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1       Figure 4 is an exploded view of the transmitter and sensor of Figure 3.

2       Figure 5 is an electrical schematic view of the sensor and transmitter of Figure 3.

3       Figure 6 is a block diagram of the major components of the sensor and transmitter of  
4       Figure 3.

5       Figure 7 is a flow chart illustrating the operation of the sensor and transmitter of Figure 3.

6       Figure 8 is a block diagram of the major components of the receiver of Figure 2.

7       Figure 9 is a flow chart illustrating the operation of the receiver for the water leveler of  
8       Figure 2.

9       **Detailed Description of the Invention**

10       Referring to Figure 1, a pool 10 is shown which contains an amount of water 12. Pool 10  
11       may be a swimming pool or some other type of pool that has a recirculation system. Pool 10 has  
12       a number of skimmers or outlets 14 (only one shown) for recirculating water. A water outflow  
13       line 16 extends downward from skimmer 14 and extends to an intake of a circulation pump 18.  
14       A water inflow line 20 extends from an output of circulation pump 18 back to pool 10. Both  
15       inflow and outflow lines 20, 16 are typically located below ground. In some instances, however,  
16       they are above ground. In general operation, circulation pump 18 continuously draws water 12  
17       from pool 10 through outflow line 16 and pumps it through inflow line 20 back into pool 10.  
18       There are one or more filters or other cleaners and perhaps a heater associated with this  
19       circulation system.

1        This system also has automatic filling equipment to replace water lost due to evaporation  
2        and other reasons. This system includes a sensor assembly 21, which may be located in one of  
3        the skimmers 14 or elsewhere. Sensor assembly 21 senses the level of water 12, and if it is  
4        below a selected level, sends a radio frequency signal to a receiver 22. Receiver 22 is located in  
5        the vicinity of circulation pump 18 and is connected to a solenoid valve 23. Valve 23 is located  
6        in inflow line 20, which is connected to a source of water, such as the city water supply. Valve  
7        23 is preferably connected to the suction side of pump 18, but it could also be connected to an  
8        inflow line separate from inflow line 20 of pump 18. Upon receiving an RF signal from sensor  
9        21, receiver 22 opens valve 23 to allow water to flow from the city supply into inflow line 20.  
10       When the water reaches an adequate level, receiver 22 cuts off valve 23.

11       Referring to Figure 2, skimmer 14 has a throat 24 for receiving water from pool 10.  
12       Throat 24 includes a port in the sidewall of the pool. A basket 26 is located within skimmer 14  
13       for filtering debris in the water as it is drawn through throat 24 and into flow line 16. In the  
14       preferred embodiment, sensor assembly 21 is mounted in throat 24, however it could be mounted  
15       elsewhere. Referring to Figures 3 and 4, sensor assembly 21 includes a sensor and transmitter 28  
16       assembly, which is a single integral unit and is referred to hereafter as sensor 28. Sensor 28  
17       includes an elongated housing 29 that is rectangular in configuration, although this could be  
18       varied. A pair of wires or probes 30 extend outward from housing 29 and alongside one of the  
19       sidewalls. One of the probes 30 is longer than the other, and probes 30 are connected to  
20       electrical circuitry inside sensor 28. Water 12 is conductive, thus the circuitry will sense when  
21       both probes 30 are immersed in water. The circuitry detects the loss in conductivity that occurs  
22       when one probe 30 is spaced above the water. Sensor 28 also has an antennae 32 for  
23       transmitting an RF signal.

1 Sensor 28 locates within a container base 34 in this embodiment. Container base 34 is a  
2 cylindrical tube that has a bottom with a plurality of holes 36 to allow water to flow into  
3 container base 34. Container base 34 has a plurality of thread segments 38 along its sidewall. A  
4 spacer 42 may be employed to extend the height of sensor 28, if needed. A container cap 40 (not  
5 shown in Fig. 3) fits over the sidewall of container base 34. Container cap 40 has internal  
6 threads that engage thread segments 38. Rotating container cap 40 in one direction relative to  
7 base 34 will unscrew it from threads segments 38 and extend the overall distance between the top  
8 of cap 40 and the bottom of container base 34. Container base 34 and container cap 40 thus  
9 telescope in length to allow sensor assembly 21 to be releasably wedged between upper and  
10 lower sides of throat 24 (Fig. 2). The user places sensor assembly 21 in throat 24 while container  
11 base 34 and container cap 40 are in a reduced length position, then rotates one relative to the  
12 other to increase the length until sensor assembly 21 is frictionally held in throat 24.

13 Figure 5 illustrates the components located and sealed within housing 29 (Fig. 4), which  
14 is waterproof. The components include a battery 44 and an internal switch 46. To reduce the  
15 chance for leakage, switch 46 is not exposed to nor accessible from the exterior of housing 29.  
16 Switch 46 is a tilt type known as a mercury switch, that turns on and off by tilting. When sensor  
17 28 is in the upright position shown in Figure 3, switch 46 will be closed. When sensor 28 is  
18 inverted or even partially inverted, switch 46 will open. This allows sensor 28 to be reset simply  
19 by inverting sensor 28 then returning it to the upright position. Sensor 28 may also be left in an  
20 off position by placing it in an inverted position. During the winter if the recirculation system is  
21 not being used, housing 29 is preferably left in an inverted position to avoid consumption of  
22 battery 44. It is not necessary to remove sensor 28 from container base 34 and cap 40 to actuate  
23 tilt switch 46.

1 Referring to Figure 5, sensor 28 also contains a conventional integrated processor circuit  
2 48 that has a number of functions. Processor 48 has an intermittent duty cycle and a sleep cycle.  
3 In the sleep cycle, processor 48 consumes much less power than when in the duty cycle. In one  
4 embodiment, processor 48 has a duty cycle every 18 milliseconds. The duration of the duty  
5 cycle is in micro seconds, thus processor 48 will be in the sleep cycle much more so than the  
6 duty cycle. By way of example, voltage is applied to probes 30 for only about 15 micro seconds  
7 during the duty cycle.

8 A conventional voltage regulator 45 is connected between battery 44 and processor 48.  
9 A conventional voltage detector circuit 47 is connected also to processor 48 and the output of  
10 voltage regulator 45 for sensing the level of the voltage. Voltage detector 47 supplies a  
11 corresponding signal to processor 48. Voltage detector 47 receives its power from voltage  
12 regulator 45, thus is turned on to sample the voltage only during the duty cycle.

13 Processor 48 is connected to one of the probes 30, the other being grounded. Amplifiers  
14 49 are connected to the probe 30 that leads to processor 48 for amplifying voltage differential  
15 between probes 30. If there is no continuity between probes 30, processor 48 provides a signal  
16 to a transmitter 50. Transmitter circuit 50 is a conventional integrated circuit that provides a  
17 digital signal to antennae 32. When instructed by processor 48, transmitter 50 provides a single  
18 digitally encoded RF signal of a selected duration, then it is turned off by processor 48.  
19 Transmitter circuit 50 also has its power input connected to a power output from processor 48.  
20 Consequently, it is turned on only when processor 48 causes transmitter 50 to send an RF signal.  
21 Processor 48 also encodes into the RF digital signal a portion that indicates that the battery level  
22 is low if such is indicated by voltage detector 47. Processor 48 will not cause transmitter 50 to  
23 send a low voltage signal until it receives a low water indication from probes 30. The low

1 voltage signal, when it occurs, is always encoded as part of the low water signal being sent  
2 from transmitter 50.

3 The basic operation of the circuitry of Figure 5 is illustrated in the block diagram of  
4 Figure 6 and flow chart of Figure 7. Power is turned on or sensor 28 reset in step 52 by closing  
5 switch 46 (Fig. 5), which occurs by inverting then returning sensor 28 to an upright position. As  
6 indicated in step 54, turning the power on starts processor 48, causing it to begin its duty and  
7 sleep cycles. Processor 48 applies voltage during the duty cycle to probes 30, as indicated by step  
8 56.

9 As indicated by step 58, processor 48 makes a determination as to whether conductivity  
10 exists between probes 30 when voltage is supplied to the probes. If so, this indicates that probes  
11 30 are in water, and processor 48 continues the duty and sleep cycles. If a lack of conductivity is  
12 detected between probes 30, step 60 indicates that a wave filter timer 61 is initiated. Wave filter  
13 timer 61 is an adjustable counter that is a part of processor 48 for avoiding spurious signals due  
14 to wave motion. Wave filter timer 61 determines how long the lack of conductivity must be  
15 present before sending a signal to the transmitter 50. For example, it may be set to count up to  
16 three minutes, and up until three minutes occurs, it will not allow a signal to be sent to  
17 transmitter 50. If during that three minute interval, processor 48 and probes 30 continuously  
18 detect a lack of conductivity during each duty cycle, then a signal is sent to transmitter 50 at the  
19 conclusion of the three minute interval, as indicated in step 62. Transmitter 50 will then send an  
20 RF signal to receiver 22 (Fig. 1) indicating that the water level is low. However, if at any time  
21 during the three minute interval of wave filter timer 61, probes 30 become immersed in water  
22 again, processor 48 will cause wave filter timer 61 to reset and stop as indicated by step 64.  
23 Wave filter timer 61 will not start counting again until processor 48 detects low water again.

1 Referring again to Figure 2, a momentary RF signal 82 is sent by transmitter 50 (Fig. 5)  
2 of sensor assembly 21 when low water is detected for a selected time period. Receiver 22  
3 receives signal 82 and transmits an open command by a wire 84 to solenoid valve 23. Solenoid  
4 valve 23 is connected in parallel with a manual valve 90, which in turn is connected to a water  
5 source 88. Water source 88 leads to the intake of pump 18 in this embodiment, although it could  
6 be a separate line from pump 18. Manual valve 90 will be normally closed, thus water will be  
7 supplied from source 88 only when solenoid valve 23 is open due to a signal received from  
8 receiver 22.

9 Figures 7 and 8 illustrate the operation of receiver 22, which is a conventional receiver  
10 except that it also incorporates an overfill timer or counter 91. As indicated in step 92, if a signal  
11 is not being received by receiver 22, solenoid valve 23 is closed, as indicated by step 94. If a  
12 signal is received by receiver 22, overfill counter 91 is started as indicated in step 96. Overfill  
13 timer 91, which is adjustable, will begin counting, as indicated by step 98 and open solenoid  
14 valve 23, as indicated by step 100 for a selected count or duration. When overfill counter 91  
15 reaches its total count, step 102 indicates that the solenoid valve 23 will be closed.

16 Although the RF signal from transmitter 50 (Fig. 6) is a single momentary signal of  
17 selected duration, such a signal will be sent by transmitter 50 during each duty cycle of processor  
18 48, as long as low water is indicated. Processor 48 will stop causing transmitter 50 to send  
19 signals only when it senses water with probes 30 (Fig. 6). Each time receiver 22 receives  
20 another signal from transmitter 50 it resets the overfill timer 91, indicated by step 96. Since  
21 these signals normally would be received each duty cycle of processor 48 until probes 30  
22 become again immersed in water, overfill timer 91 will normally not reach the total count until  
23 probes 30 become immersed again. Once probes 30 become immersed, overfill timer 91 will

1 then count up to the selected number without being reset, at which time it would provide a signal  
2 to close valve 23, as indicated in step 102. Overfill timer 91 thus assures that a selected overfill  
3 will occur after probes 30 are again immersed in water. For example, the overfill could be in a  
4 typical pool about 3/8ths of an inch as measured on probes 30 (Figure 4).

5 In addition to overfill timer 91, there is also a fault detection timer that closes valve 23 to  
6 stop water from entering the pool if valve 23 has been open for a selected time duration, such as  
7 30 minutes. This duration is set long enough to indicate that a fault is occurring and that overfill  
8 timer 91 should have closed valve 23 long before.

9 The system has significant advantages. The main power switch is fully sealed within the  
10 unit thus reducing the possibility of leakage or deterioration. This allows the circuitry to be reset  
11 or turned off without accessing an external switch. The user simply inverts the unit then returns  
12 it to its upright condition. The unit is readily removable from the throat of the skimmer by  
13 slightly unscrewing the cap relative to the base to shorten the overall length of the unit. There is  
14 no need to remove the transmitter and sensor from the container to turn it on and off.

15 The overfill timer associated with the sensor provides a means for avoiding spurious  
16 signals due to wave movement. The overfill timer of the receiver reduces the number of signals  
17 that would otherwise be transmitted by the transmitter. It does this by overfilling each time the  
18 water is low. Reducing the signals sent by the transmitter prolongs the life of the battery.

19 While the invention has been shown in only one of its forms, it should be apparent to  
20 those skilled in the art that it is not so limited but susceptible to various changes without  
21 departing from the scope of the invention.